Speech-Driven Realtime Lip-Synch Animation with Viseme-Dependent Filters

Supplemental Material for SIGGRAPH 2013 Poster

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Introduction

Motivation

Lip-synching is one of fundamental components for creating facial animation. Mouth movement is synchronized along with the speech, when a character utters a word or phrase. Especially, speech-driven realtime lip-synching animation is useful for helping speech communication.

Aim

Realizing speech-driven realtime lip-synching based on blendshapes, linear shape interpolation model.

Problem

Simple solution is to construct a mapping between speech and mouth-shape directly. These direct mapping approaches can realize lip-synching with small delay. However it is sometimes unnatural since mouth movement is mismatched between the speaker and the pre-designed characters.

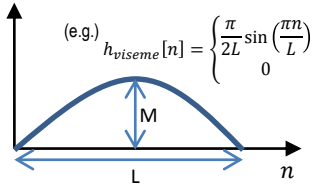
Our solution

we consider customization of mouth movement by viseme-dependent filters designed for each mouth shape of given characters.

Viseme-dependent Filter

$h_{viseme}[n]$

(e.g.) $h_{viseme}[n] = \begin{cases} \frac{\pi}{2L}\sin\left(\frac{\pi n}{L}\right) & (0 \le n \le L) \\ 0 & (otherwise) \end{cases}$



$M = \frac{\pi}{2L}$

L : filter length (#tap)

⟹ Transition Time between Mouth Shapes

$M = \max_n(h_{viseme}[n]) = \frac{\pi}{2L}$

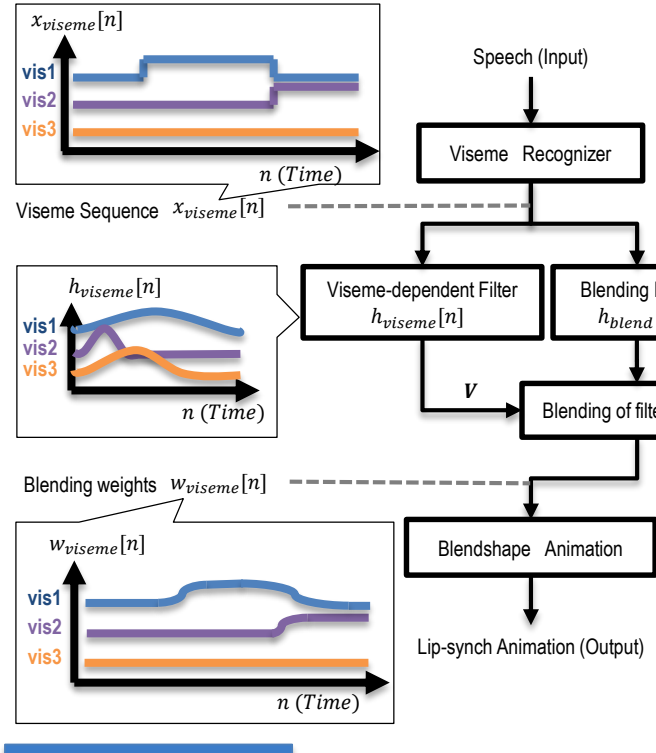
∝ Maximum Mouth Movement Speed

How to decide this parameters?

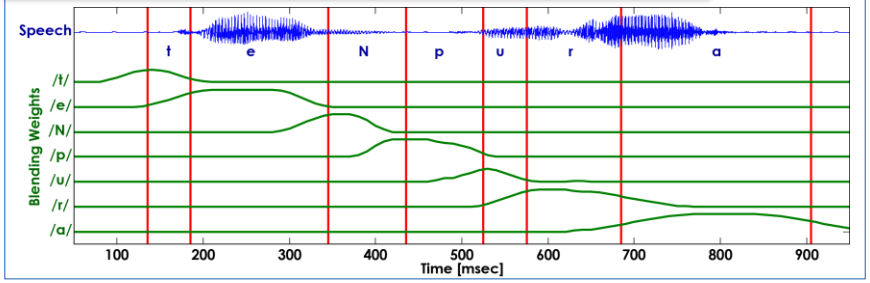
[default] depends on Euclid distance between a target-shape and a neutral-shape (*normalize maximum mouth movement speed*)

[customize] depends on the desirable transition time (*eg. Consonants /p/, /b/, and /m/*)

Processing Flow



Example of Our Result (Speech & Blending Weights)



Constraints of Blending Filter

$$\sum_n h_{blend}[n] = 1, \quad h_{blend}[n] > 0$$

Notations Note: '*' means a convolution operator

$$V = \begin{bmatrix} h_{vis_1} * x_{vis_1} & h_{vis_2} * x_{vis_1} & \cdots & h_{vis_N} * x_{vis_1} \\ h_{vis_1} * x_{vis_2} & h_{vis_2} * x_{vis_2} & \cdots & h_{vis_N} * x_{vis_2} \\ \vdots & \vdots & \ddots & \cdots \\ h_{vis_1} * x_{vis_N} & h_{vis_2} * x_{vis_N} & \cdots & h_{vis_N} * x_{vis_N} \end{bmatrix}$$

$$B = \begin{bmatrix} h_{blend} * x_{vis_1} \\ h_{blend} * x_{vis_2} \\ \vdots \\ h_{blend} * x_{vis_N} \end{bmatrix} \qquad W = \begin{bmatrix} w_{vis_1} \\ w_{vis_2} \\ \vdots \\ w_{vis_N} \end{bmatrix}$$

Viseme Recognizer

Viseme recognizer iterates the following processes at a constant frequency:

[Step.1] Estimates phonemes and its duration by using an HMM-based speech recognizer from observing input speech at this time.

[Step.2] Convert phoneme to viseme based on table lookup.

Phoneme-Viseme Mapping Table (Japanese)

Viseme ID	Phonemes
1	r, ry
2	b, by, m. my, p, py
3	t
4	d, n, ny
5	g, gy, hy, k, ky, N
6	f
7	ch, dy, j, s, sh, ts, z
8	w
9	a
10	I
11	u
12	e
13	o

Note: Viseme is a basic unit of mouth shapes that are classified visually

Result & Discussion

Our lip-synch system worked well with about 0.3 sec of delay from the input speech.

Factors of its delay:

(1) Viseme recognition also needs some processing time.

Delay ⟷ (tradeoff) ⟷ Accuracy of viseme recognition results

(2) Length of the filters for generating blending weights is also related to the delay of the animation

Delay ⟷ (tradeoff) ⟷ Smoothness of mouth shape transition

(3) Minimum delay of speech output depends on the hardware specification (*eg. delay of sound device*)

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